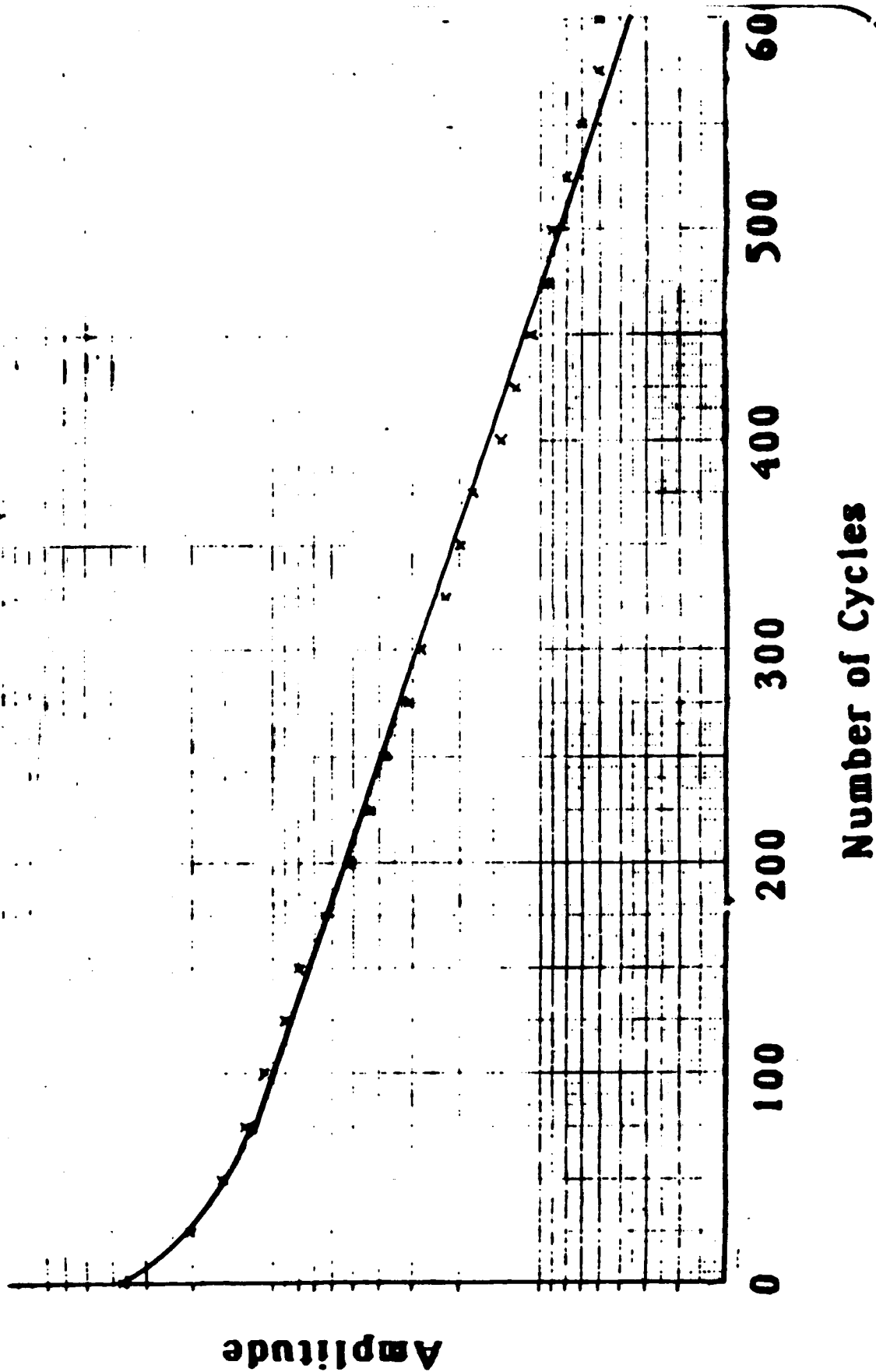


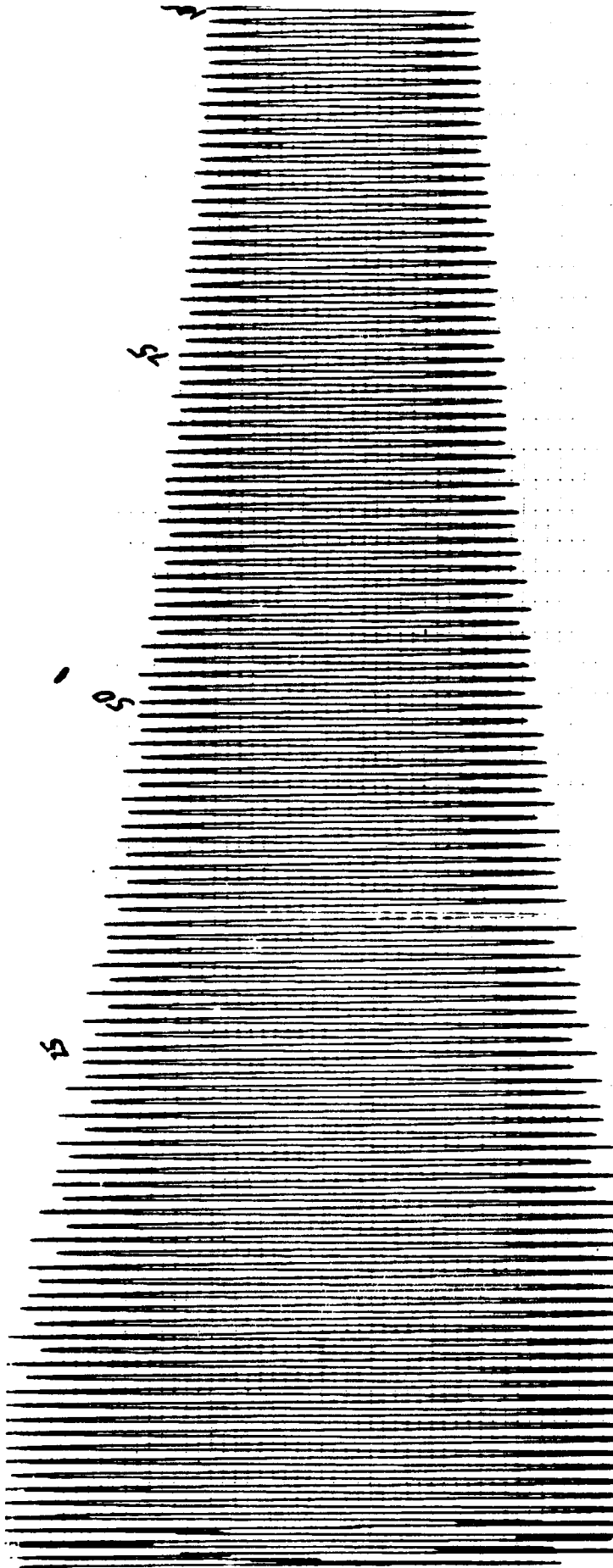
**ON MODELLING NONLINEAR
DAMPING IN DISTRIBUTED
PARAMETER SYSTEMS**

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Los Angeles, California

12 July 1988

SCOLE DAMPING





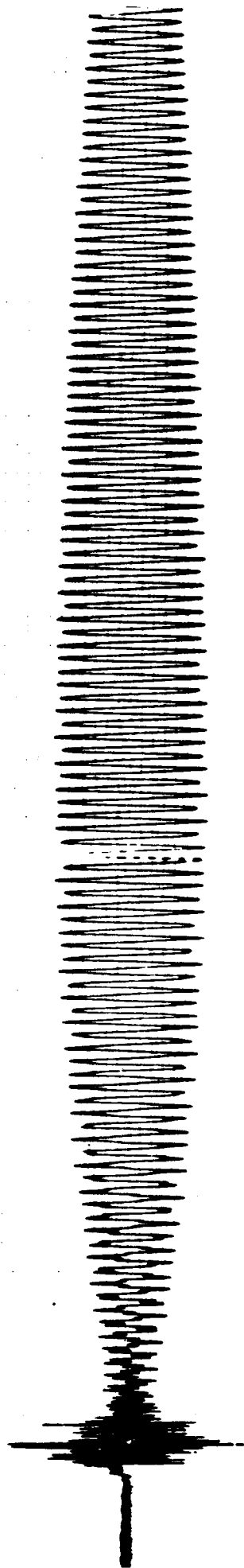
REFLECTOR X ACCELEROMETER

-21 W- 5 SECONDS

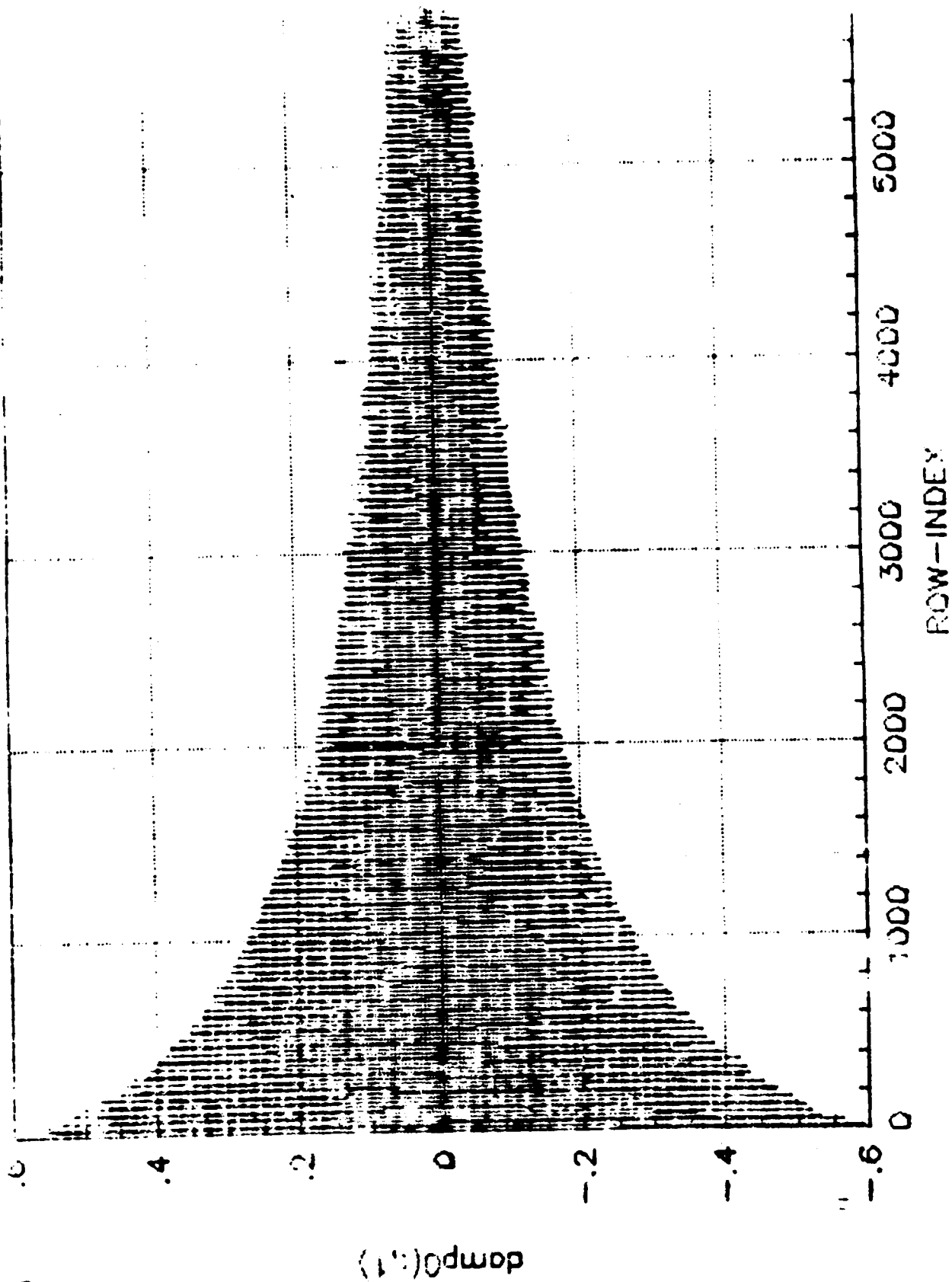
$U = \pm 12"$

0.7

653



TIME →



With mass

654

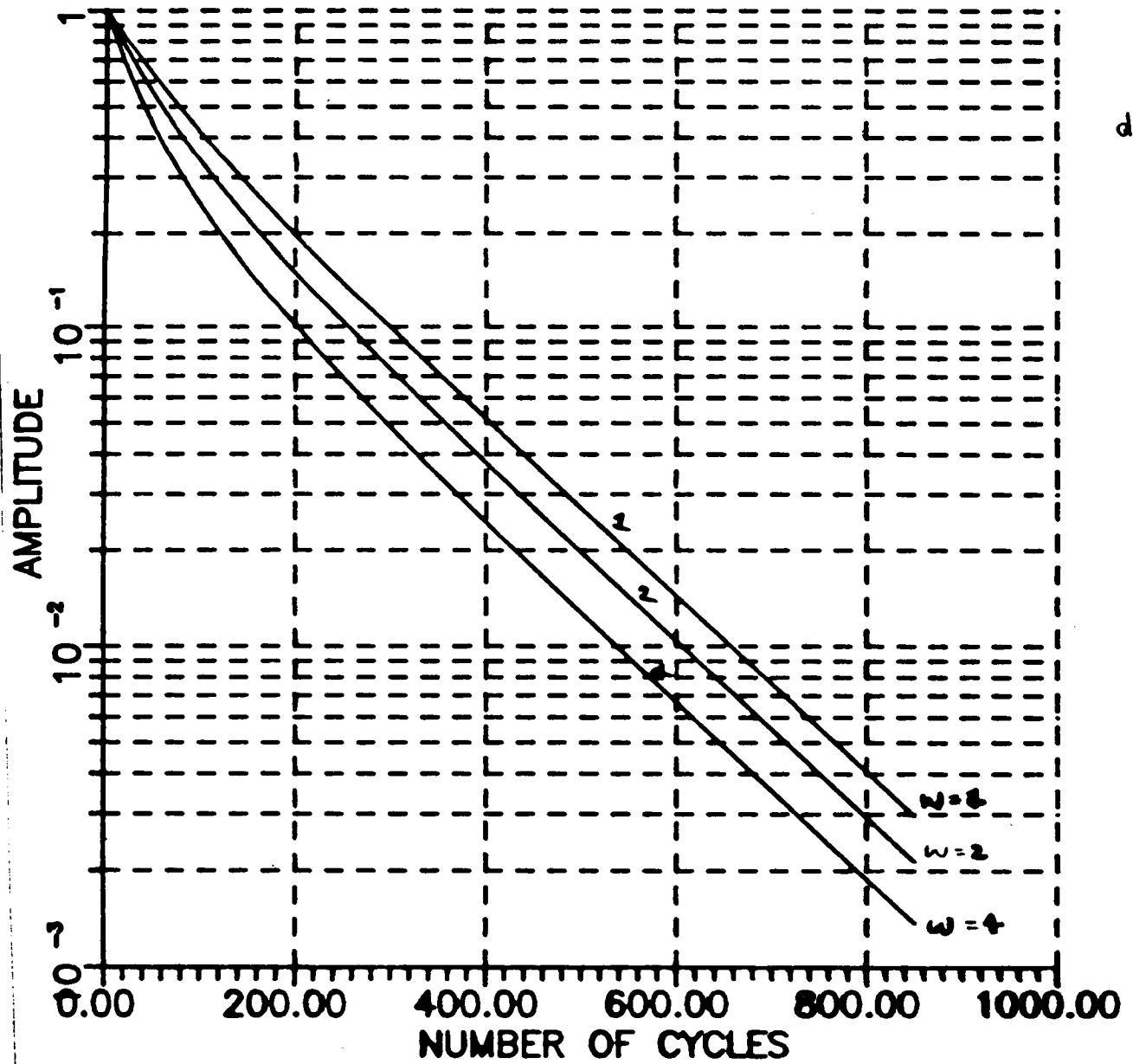
In One Dimension

Without hysteresis

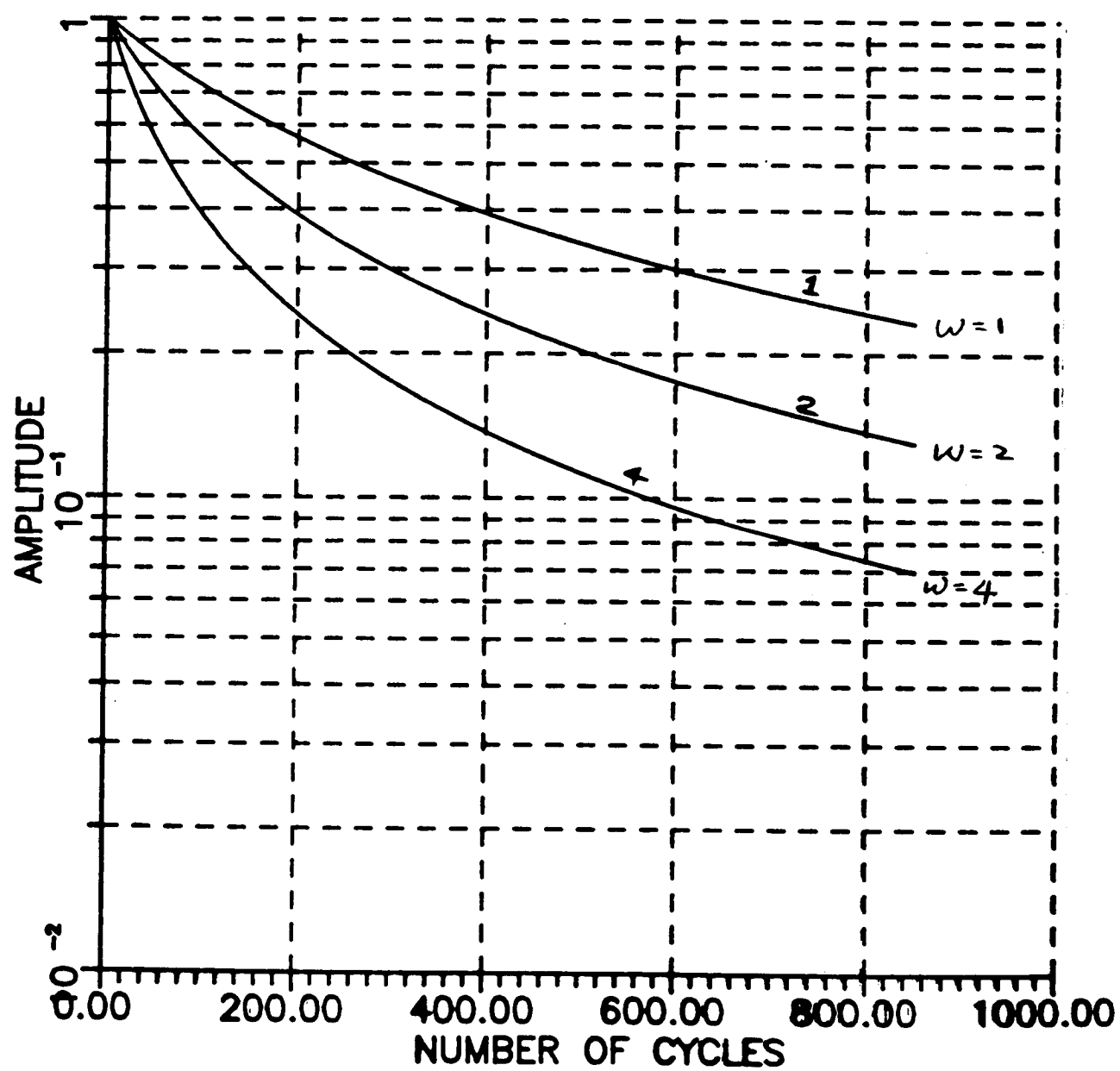
$$\begin{aligned} \ddot{x}(t) &+ \omega^2 x(t) + 2\omega\zeta\dot{x}(t) \\ &+ \gamma x(t)^{2m} |x(t)|^\alpha \dot{x}(t)^{2n+1} |\dot{x}(t)|^\beta \\ &+ Bu(t) + FN(t) \\ &= 0 \end{aligned}$$

$$0 \leq \alpha, \beta \leq 1 .$$

NONLINEAR DAMPING



NONLINEAR DAMPING: $\zeta = 0$



Beam Model

$$\begin{aligned} \ddot{u}(s, t) + \lambda u''''(s, t) - 2\zeta\sqrt{\lambda} \dot{u}''(s, t) \\ - \gamma \left(\int_0^L u'(s, t) \dot{u}'(s, t) ds \right)^{2(n+\beta)+1} u''(s, t) \\ = 0, \end{aligned}$$

$$0 < s < L; \quad 0 < t$$

n : zero or positive integer

$$0 \leq \beta < \frac{1}{2}$$

ζ : Linear Damping Ratio

Prime represents space derivative

Dot represents time derivative

$$A \sim \frac{d^4}{ds^4} : \text{clamped beam}$$

$$A\phi_k = \omega_k^2 \phi_k$$

$$\sqrt{A} \phi_k = \omega_k \phi_k$$

$$\sqrt{A} \sim (-1) \frac{d^2}{ds^2}$$

$$\int_0^L u'(s, t) \dot{u}'(s, t) ds$$

$$= \int_0^L [u(s, t) \dot{u}'(s, t)]$$

$$- \int_0^L u(s, t) \dot{u}''(s, t) ds$$

$$x(t) = u(\cdot, t)$$

$$\rightarrow \approx [x(t), \sqrt{A} \dot{x}(t)]$$

$$F(x, D\dot{x}) = \gamma([x, \sqrt{A} \dot{x}])^{2(n+\beta)+1} \sqrt{A} x$$

$$\ddot{x}(t) + \lambda Ax(t) + D\dot{x}(t)$$

$$+ F(x(t), D\dot{x}(t)) + Bu(t)$$

$$= 0$$

$$D = 2\zeta\sqrt{\lambda}\sqrt{A}$$

$$x(t) = u(\cdot, t)$$

$$\begin{aligned} M\ddot{x}(t) + \lambda Ax(t) + D\dot{x}(t) \\ + F(x(t), D\dot{x}(t)) + Bu(t) = 0 \end{aligned}$$

Energy

$$\begin{aligned} E(t) &= \frac{1}{2} \{ [\dot{x}(t), \dot{x}(t)] + \lambda [Ax(t), x(t)] \} \\ \frac{d}{dt} E(t) &= [\ddot{x} + \lambda Ax, \dot{x}] \\ &= -[D\dot{x}(t), \dot{x}(t)] - [F(x(t), D\dot{x}(t)), \dot{x}(t)] \end{aligned}$$

$$[F(x, D\dot{x}), \dot{x}(t)] = ([x, \sqrt{A} \dot{x}])^{2(n+\beta)+2}$$

$$\geq 0$$

$$\Rightarrow \frac{dE(t)}{dt} \leq 0$$

$$x = a_k(t)\phi_k$$

$$F(x, D\dot{x})$$

$$= \gamma(a_k(t) \omega_k \dot{a}_k(t))^{2(n+\beta)+1} \omega_k a_k(t) \phi_k$$

$$= \gamma a_k(t)^{2(n+\beta)+2} \omega_k^{2(n+\beta)+2} \dot{a}_k(t)^{2(n+\beta)+1} \phi_k$$

$$\alpha = \beta ; \quad m = n$$

$$x(t) \; = \; a_k(t)\phi_k$$

$$\begin{aligned} \ddot{a}_k(t) \; + \; \lambda \omega_k^2 a_k(t) \; + \; 2 \zeta \sqrt{\lambda} \; \omega_k \dot{a}_k(t) \\ + \; \gamma (a_k(t) \dot{a}_k(t) \omega_k)^{2(n+\beta+1)} \; \omega_k a_k(t) \\ = \; 0 \end{aligned}$$

$$\begin{aligned} \gamma a_k(t)^{2m} \; |a_k(t)|^\alpha \; |\dot{a}_k(t)|^\beta \; \dot{a}_k(t)^{2n+1} \\ \sim \; m \; = \; n \; ; \end{aligned}$$

$$\alpha \; = \; \beta$$

Alternate Form

$$\begin{aligned} u(s, t) + \lambda u''''(s, t) - 2\zeta\sqrt{\lambda} \dot{u}''(s, t) \\ + \gamma \left(\int_0^L u(s, t) \dot{u}''(s, t) ds \right)^{2(n+\beta)+1} u''(s, t) \\ = 0, \end{aligned}$$

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